

Phase 1 of the simplex algorithm

G. Ferrari Trecate

Dipartimento di Ingegneria Industriale e dell'Informazione
Università degli Studi di Pavia

Industrial Automation

Introduction

Reference problem

$$\begin{array}{ll} \max & c^T x \\ Ax & = b \\ x & \geq 0 \end{array} \quad (\text{LP-S})$$

Assumption: $b \geq 0$

↳ without loss of generality (if $b_i < 0$ multiply by -1 both sides of $a_{i,\cdot} x = b_i$)

Problem: Compute a BFS or conclude (LP-S) is infeasible

Key trick

Build the auxiliary problem

$$\min_{x, y} \sum_{i=1}^m g_i \quad (\text{LP-AUX})$$

$$Ax + y = b$$

$$x \geq 0, y \geq 0$$

- $y \in \mathbb{R}^m$ are called **artificial variables**
- In matrix form we have

$$\tilde{x} = \begin{bmatrix} x \\ y \end{bmatrix}$$

$$\tilde{A} = [A \ I] \longrightarrow$$

$$\min [\overbrace{0 \dots 0}^{n \text{ zeros}} \ \overbrace{1 \dots 1}^{m \text{ ones}}] \tilde{x}$$

$$\tilde{A}\tilde{x} = b$$

$$\tilde{x} \geq 0$$

Properties of the auxiliary problem

$$\min_{x, y} \sum_{i=1}^m g_i \quad (\text{LP-AUX})$$

$$Ax + y = b$$

$$x \geq 0, y \geq 0$$

- (LP-AUX) is always feasible because $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ b \end{bmatrix}$ is a BFS (the one associated to the basis $B = I$ contained in \hat{A})
- Let z_{AUX}^* be the optimal cost of (LP-AUX) and x^*, y^* be optimizers

$$z_{\text{AUX}}^* = 0 \iff \sum_{i=1}^m y_i^* = 0 \iff y^* = 0 \iff \begin{cases} Ax^* = b \\ x^* \geq 0 \end{cases} \iff x^* \text{ is a feasible solution to (LP-S)}$$

Thm. If $\tilde{x}^T = [x^* \ 0]$ is an optimal solution to (LP-Aux), then x^* is a **BFS** to (LP-S)

Tableau form of phase 1

- Initial tableau for (LP-Aux). Assumption: $b \geq 0$

row 0 →	0	x_1	...	x_n	y_1	...	y_m
	0	0	...	0	1	...	1
row 1 →	b	A			I		
⋮							
row m →							

In order to put it in canonical form w.r.t. the variables y_1, \dots, y_m , subtract rows 1, ..., m from row 0 (it is equivalent to pivoting on all 1's on the diagonal of I)

• How to get the initial tableau of phase 2 from the final tableau of phase 1. Only two cases are possible

• Case 2: all y_i are NBVs

Let x_{i_1}, \dots, x_{i_m} be BVs

	x_1	\dots	x_n	y_1	\dots	y_m
0	\bar{z}			*		
x_{i_1} \dots x_{i_m}	\bar{A}			*		
	\bar{b}					

Initial tableau
for phase 2

	x_1	\dots	x_n
0	\bar{c}		
	\bar{A}		
	\bar{b}		

uninteresting entries

cost of (LP-5)

Then we put the tableau in canonical form w.r.t. x_{i_1}, \dots, x_{i_m} through suitable pivot operations

- Case b: a variable y_h is basic. Let the associated row be the i -th one

	0	x_1	...	x_n		y_1	...	y_h	...	y_m
...										
y_h	0	$\bar{a}_{i,1}$...	$\bar{a}_{i,n}$...	0	1
...										

↳ the BFS must be degenerate! Look for another representation of the same vertex without auxiliary BVs

- If some $\bar{a}_{i,s}$ is nonzero, perform a pivot on $\bar{a}_{i,s}$
 ↳ y_h leaves the basis and the cost remains 0

- If all $\bar{a}_{i,j}$ are zero, the i -th row can be removed from the tableau
↳ rank(A) was not maximal and some row of A could have been removed from the beginning

After these operations, proceed as in Case a.

Ex.

$$\begin{aligned} \min \quad & x_1 + x_3 \\ & x_1 + 2x_2 \leq 5 \\ & x_2 + 2x_3 = 6 \\ & x_1, x_2, x_3 \geq 0 \end{aligned}$$

Solve the LP problem running the simplex algorithm

Put the LP in standard form

$$\begin{aligned} \min \quad & x_1 + x_3 \\ & x_1 + 2x_2 + x_4 = 5 \\ & x_2 + 2x_3 = 6 \\ & x_1, x_2, x_3, x_4 \geq 0 \end{aligned} \quad \begin{array}{l} \text{slack variable} \\ \text{(LP-S)} \end{array}$$

Verify that $b \geq 0$. $b = \begin{bmatrix} 5 \\ 6 \end{bmatrix}$ OK!

Run simplex phase 1

- Build the auxiliary problem

the auxiliary pbl is always a "min"

$$\begin{aligned} \min \quad & y_1 + y_2 \\ & x_1 + 2x_2 + x_4 + y_1 = 5 \\ & x_2 + 2x_3 + y_2 = 6 \\ & x_1, \dots, x_4 \geq 0, \quad y_1, y_2 \geq 0 \end{aligned}$$

auxiliary vars

- Initial tableau

row 0 →

	x_1	x_2	x_3	x_4	y_1	y_2
0	0	0	0	0	1	1
5	1	2	0	1	1	0
6	0	1	2	0	0	1

Pivoting on these elements = subtract rows 1 and 2 from row 0

- Put the tableau in standard form w.r.t. variables y_1 and y_2

• Run phase 2 as a subroutine of phase 1

		x_1	x_2	x_3	x_4	s_1	s_2				
-11		-1	-3	-2	-1	0	0	- [-5 -1 -2 0 -1 -1 0]			
s_1	5	1	2	0	1	1	0	↑			
s_2	6	0	1	2	0	0	1	← - 0			

$r_F \neq 0 \rightarrow$ Bland's rule: x_1 enters the basis.

Ratios: $\frac{5}{1} \rightarrow s_1$ leaves the basis
 $\frac{6}{0}$

$Aux = [5 \quad 1 \quad 2 \quad 0 \quad 1 \quad 1 \quad 0]$ - - -

		x_1	x_2	x_3	x_4	s_1	s_2	
	-6	0	-1	-2	0	1	0	$-[-\frac{5}{2} \quad -\frac{1}{2} \quad -1 \quad 0 \quad -\frac{1}{2} \quad -\frac{1}{2} \quad 0]$
x_1	5	1	2	0	1	1	0	
s_2	6	0	1	2	0	0	1	$-[\frac{5}{2} \quad \frac{1}{2} \quad 1 \quad 0 \quad \frac{1}{2} \quad \frac{1}{2} \quad 0]$

$r_F \neq 0 \rightarrow$ Bland's rule: x_2 enters the basis.

Ratios: $s_2 \rightarrow x_1$ leaves the basis

$$Aux = \left[\frac{5}{2} \quad \frac{1}{2} \quad 1 \quad 0 \quad \frac{1}{2} \quad \frac{1}{2} \quad 0 \right]$$

		x_1	x_2	x_3	x_4	y_1	y_2	
	$-\frac{7}{2}$	$\frac{1}{2}$	0	-2	$\frac{1}{2}$	$\frac{3}{2}$	0	- $[-\frac{7}{2} \quad \frac{1}{2} \quad 0 \quad -2 \quad \frac{1}{2} \quad \frac{1}{2} \quad -1]$
x_2	$\frac{5}{2}$	$\frac{1}{2}$	1	0	$\frac{1}{2}$	$\frac{1}{2}$	0	- 0
y_2	$\frac{7}{2}$	$-\frac{1}{2}$	0	2	$-\frac{1}{2}$	$-\frac{1}{2}$	1	

$r_F \neq 0 \rightarrow$ Bland's rule: x_3 enters the basis.

Ratios: $\frac{5}{2}$

$\frac{7}{2} \rightarrow y_2$ leaves the basis

$$Aux = \left[\frac{7}{4} \quad -\frac{1}{4} \quad 0 \quad 1 \quad -\frac{1}{4} \quad -\frac{1}{4} \quad \frac{1}{2} \right]$$

		x_1	x_2	x_3	x_4	s_1	s_2
	0	0	0	0	0	1	1
x_2	$\frac{5}{2}$	$\frac{1}{2}$	1	0	$\frac{1}{2}$	$\frac{1}{2}$	0
x_3	$\frac{7}{4}$	$-\frac{1}{4}$	0	1	$-\frac{1}{4}$	$-\frac{1}{4}$	$\frac{1}{2}$

→ zero cost: (LP-S) is feasible

- Compute the initial tableau for phase 2

		x_1	x_2	x_3	x_4
	0	1	0	1	0
x_2	$\frac{5}{2}$	$\frac{1}{2}$	1	0	$\frac{1}{2}$
	$\frac{7}{4}$	$-\frac{1}{4}$	0	1	$-\frac{1}{4}$

→ cost of (LP-S)

→ Initial BVs: x_2 and x_3

Remark: x_2 is already a dependent variable but x_3 is not

Run simplex phase 2

. Put the initial tableau in canonical form w.r.t. the initial basis

		x_1	x_2	x_3	x_4
	0	1	0	1	0
x_2	$\frac{5}{2}$	$\frac{1}{2}$	1	0	$\frac{1}{2}$
	$\frac{7}{4}$	$-\frac{1}{4}$	0	1	$-\frac{1}{4}$

→ It is enough to turn x_3 into a dependent variable by pivoting on the circled entry
↳ This amounts to subtract row 2 from row 0

		x_1	x_2	x_3	x_4
	$-\frac{7}{4}$	$\frac{5}{4}$	0	0	$\frac{1}{4}$
x_2	$\frac{5}{2}$	$\frac{1}{2}$	1	0	$\frac{1}{2}$
x_3	$\frac{7}{4}$	$-\frac{1}{4}$	0	1	$-\frac{1}{4}$

$r_F \geq 0 \rightarrow$ optimal solution: STOP.

• Read the results from the final tableau

Optimal cost: $\frac{7}{4}$

Optimal BFS $x_B^* = \begin{bmatrix} x_2^* \\ x_3^* \end{bmatrix} = \begin{bmatrix} 5/2 \\ 7/4 \end{bmatrix} \rightarrow x^* = \begin{bmatrix} 0 \\ 5/2 \\ 7/4 \\ 0 \end{bmatrix}$

Degeneracy and finite termination of the simplex algorithm

Ex.

$$\max x \quad 2x_1 + x_2$$

$$3x_1 + x_2 + x_3 = 6$$

$$x_1 - x_2 + x_4 = 2$$

$$x_2 + x_5 = 3$$

$$x_1, \dots, x_5 \geq 0$$

(LP-5)

Assume in phase 2 one computes the tableau

		x_1	x_2	x_3	x_4	x_5	
	-4	0	3	0	2	0	$-[0 \ 0 \ 3 \ \frac{3}{4} \ \frac{-1}{4} \ 0]$
x_3	0	0	4	1	-3	0	
x_1	2	1	-1	0	1	0	$-[0 \ 0 \ -1 \ \frac{-1}{4} \ \frac{3}{4} \ 0]$
x_5	3	0	1	0	0	1	$-[0 \ 0 \ 1 \ \frac{1}{4} \ \frac{-3}{4} \ 0]$

$r_F \neq 0 \rightarrow$ Bland's rule: x_2 enters the basis.

Ratios: $\frac{0}{4} \rightarrow x_3$ leaves the basis but the cost cannot change

$\frac{2}{-1}$

$\frac{3}{1}$

$$AUX = [0 \ 0 \ 1 \ \frac{1}{4} \ \frac{-3}{4} \ 0]$$

	x_1	x_2	x_3	x_4	x_5
-4	0	0	$-\frac{3}{4}$	$\frac{17}{4}$	0
x_3	0	1	$\frac{1}{4}$	$-\frac{3}{4}$	0
x_1	2	0	$\frac{1}{4}$	$\frac{1}{4}$	0
x_5	3	0	$-\frac{1}{4}$	$\frac{3}{4}$	1

↳ New BFS but same cost

- Rmk.**
- If a vertex is defined by more than n hyperplanes, there are multiple feasible basis corresponding to it
 - On the example, further iterations of phase 2 will generate other vertices with higher cost

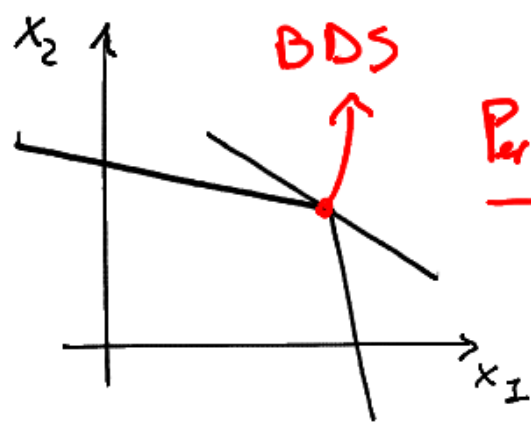
Pbl: How to guarantee, in general that the simplex algorithm does not cycle forever among degenerate basis?

Anti-cycling rules

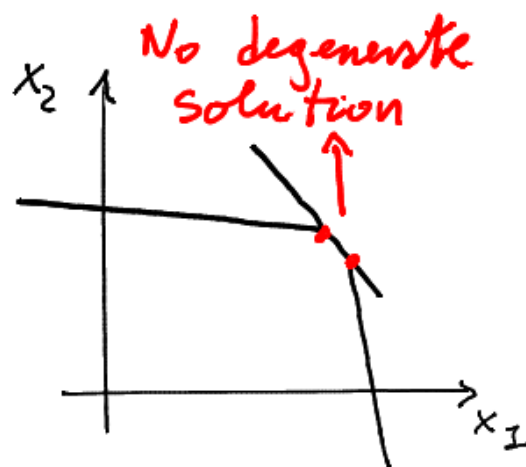
1) Bland's rule

Thm. The simplex algorithm with Bland's rule ends or at most $\binom{n}{m}$ iterations.

2) Random "small" perturbations of constraints after detecting a cycle



Perturbation



↳ Pbl. Perturbations may compromise feasibility
↳ Several heuristics available ...